Coinductive Logic Programming for Type Inference

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Motivation

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Things I wanted to understand ever since were:
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Constraints and LP in Type inference

- Hindley-Milner Type inference [Milner78, Damas&Milner82] (used in ML, OCAML, Haskel, and some other languages) was based on first-order unification, and simultaneous generation and solving of constraints.
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If CLP(X) is strong enough to substitute Hindley-Milner type inference, where does Co-LP come in?
Recursion and Corecursion in Logic Programming

Example

\[
\begin{align*}
nat(0) & \leftarrow \\
nat(s(x)) & \leftarrow \ nat(x) \\
list(nil) & \leftarrow \\
list(cons\ x\ y) & \leftarrow \ nat(x),\ list(y)
\end{align*}
\]

Example

\[
\begin{align*}
bit(0) & \leftarrow \\
bit(1) & \leftarrow \\
stream(cons\ (x,y)) & \leftarrow \ bit(x),\ stream(y)
\end{align*}
\]
SLD-resolution (+ unification and backtracking) behind LP derivations.

Example

\[
\begin{align*}
\text{nat}(0) & \leftarrow \\
\text{nat}(s(x)) & \leftarrow \text{nat}(x) \\
\text{list}(\text{nil}) & \leftarrow \\
\text{list}(%x\ y) & \leftarrow \text{nat}(x), \\
& \quad \text{list}(y)
\end{align*}
\]

\[
\begin{align*}
\leftarrow \text{list}(\text{cons}(x, y)) \\
& \leftarrow \text{nat}(x), \text{list}(y)
\end{align*}
\]
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Example

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list(cons \ x \ y) & \leftarrow nat(x), \\
& \quad \text{list}(y)
\end{align*}

\[
\begin{align*}
& \leftarrow \text{list}(\text{cons}(x, y)) \\
& \quad \leftarrow \text{nat}(x), \text{list}(y) \\
& \quad \quad \leftarrow \text{list}(y) \\
& \quad \quad \quad \leftarrow \Box
\end{align*}
\]

The answer is $x/O, \ y/nil$, but we can get more substitutions by backtracking. We can backtrack infinitely many times, but each time computation will terminate.
Things go wrong

Example

\[\text{bit}(0) \leftarrow\]
\[\text{bit}(1) \leftarrow\]
\[\text{stream}(\text{scons } x \ y) \leftarrow\]
\[\quad \text{bit}(x), \text{stream}(y)\]
Things go wrong

Example

\[
\begin{align*}
\text{bit}(0) & \leftarrow \\
\text{bit}(1) & \leftarrow \\
\text{stream}(\text{scons } x y) & \leftarrow \\
& \quad \text{bit}(x), \text{stream}(y)
\end{align*}
\]

No answer, as derivation never terminates.
Things go wrong

Example

\begin{align*}
\text{bit}(0) & \leftarrow \\
\text{bit}(1) & \leftarrow \\
\text{stream}(\text{scons } x \ y) & \leftarrow \\
& \quad \text{bit}(x), \text{stream}(y) \\
& \quad \text{stream}(y) \\
& \quad \text{bit}(x_1), \text{stream}(y_1) \\
& \quad \text{stream}(y_1) \\
& \quad \text{bit}(x_2), \text{stream}(y_2) \\
& \quad \text{stream}(y_2) \\
& \vdots
\end{align*}

No answer, as derivation never terminates.
Semantics may go wrong as well.
Use normal SLD-resolution but add a new rule:
If a formula repeatedly appears as a resolvent (modulo $\alpha$-conversion), then conclude the proof.

Example

\[
\begin{align*}
\text{bit}(0) & \leftarrow \\
\text{bit}(1) & \leftarrow \\
\text{stream}(\text{scons} \; x \; y) & \leftarrow \\
& \quad \text{bit}(x), \text{stream}(y) \\
& \quad \text{stream}(\text{scons}(x, y)) \\
& \quad \text{bit}(x_1), \text{stream}(y_1) \\
& \quad \text{stream}(y_1) \\
& \quad \square
\end{align*}
\]
Use normal SLD-resolution but add a new rule:

If a formula repeatedly appears as a resolvent (modulo $\alpha$-conversion), then conclude the proof.

**Example**

\[
\begin{align*}
\text{bit}(0) & \leftarrow \\
\text{bit}(1) & \leftarrow \\
\text{stream}(\text{scons } x \ y) & \leftarrow \\
& \quad \text{bit}(x), \text{stream}(y) \\
\end{align*}
\]

The answer is: $x/0, y/\text{cons}(x_1, y_1)$. 

\[
\begin{align*}
\leftarrow \text{stream}(\text{scons}(x, y)) \\
& \quad \leftarrow \text{bit}(x), \text{stream}(y) \\
& \quad \leftarrow \text{stream}(y) \\
& \quad \leftarrow \text{bit}(x_1), \text{stream}(y_1) \\
& \quad \leftarrow \text{stream}(y_1) \\
& \quad \square
\end{align*}
\]
Drawbacks:

- ... cannot mix induction and coinduction. — All clauses need to be marked as inductive or coinductive in advance.
- Can deal only with restricted sort of structures — the ones having finite regular pattern.

Example

<table>
<thead>
<tr>
<th>0::</th>
<th>1::</th>
<th>0::</th>
<th>1::</th>
<th>0::</th>
<th>...</th>
<th>may be captured by such programs.</th>
</tr>
</thead>
<tbody>
<tr>
<td>1::</td>
<td>2::</td>
<td>3::</td>
<td>4::</td>
<td>5::</td>
<td>...</td>
<td>may not</td>
</tr>
<tr>
<td>π</td>
<td>represented as a stream may not.</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- the derivation itself is not really a corecursive process.
Solution - 2. Coinductive LP in [Komendantskaya, Power CSL’11]

... arose from considerations valid for coalgebraic semantics of logic programs
Algebraic and coalgebraic semantics for LP

Least fixed point of $T_P$

Algebraic fibrational semantics

Greatest fixed point of $T_P$

Coalgebraic fibrational semantics

Finite SLD-derivations

Finite and Infinite SLD-derivations
Algebraic and coalgebraic semantics for LP

Greatest fixed point of $T_P$

Finite and Infinite SLD-derivations

Coalgebraic fibrational semantics

Coalgebraic Logic programming
Solution - 2. Coinductive LP in [Komendantskaya, Power CSL’11]

- ... arose from considerations valid for coalgebraic semantics of logic programs
  Technically:
- features parallel derivations;
- it is not a standard SLD-resolution any more, e.g. unification is restricted to term matching;
Coinductive trees

**Definition**

Let $P$ be a logic program and $G \leftarrow A$ be an atomic goal. The *coinductive derivation tree* for $A$ is a tree $T$ satisfying the following properties.

- $A$ is the root of $T$.
- Each node in $T$ is either an and-node or an or-node.
- Each or-node is given by $\bullet$.
- Each and-node is an atom.
- For every and-node $A'$ occurring in $T$, there exist exactly $m > 0$ distinct clauses $C_1, \ldots, C_m$ in $P$ (a clause $C_i$ has the form $B_i \leftarrow B_{i1}^1, \ldots, B_{in_i}^i$, for some $n_i$), such that $A' = B_1\theta_1 = \ldots = B_m\theta_m$, for some substitutions $\theta_1, \ldots, \theta_m$, then $A'$ has exactly $m$ children given by or-nodes, such that, for every $i \in m$, the $i$th or-node has $n_i$ children given by and-nodes $B_{i1}\theta_i, \ldots, B_{in_i}\theta_i$. 
An Example

\[ \theta_1 \rightarrow \]

\text{stream}(x)
An Example

\[ \theta_1 \]
\[
\text{stream}(x) \\
\rightarrow \\
\text{stream}(\text{scons}(z, y))
\]

\[ \theta_2 \ldots \theta_3 \]
\[
\text{bit}(z) \quad \text{stream}(y)
\]

Answers for \( x \): \( \text{cons}(z, y) \) and \( \text{cons}(0, \text{cons}(y_1, z_1)) \). It's a different (corecursive) approach to what a "terminating derivation" is.
An Example

\[ \theta_1 \]

\[ \text{stream}(x) \]

\[ \stackrel{\theta_2}{\Rightarrow} \ldots \stackrel{\theta_3}{\Rightarrow} \]

\[ \text{stream}(\text{scons}(z, y)) \]

\[ \text{bit}(z) \quad \text{stream}(y) \]

\[ \text{stream}(\text{scons}(0, \text{scons}(y_1, z_1))) \]

\[ \text{bit}(0) \quad \text{stream}(\text{scons}(y_1, z_1)) \]

\[ \square \quad \text{bit}(y_1) \quad \text{stream}(z_1) \]

Answers for \( x \): \( \text{cons}(z, y) \) and \( \text{cons}(0, \text{cons}(y_1, z_1)) \). It's a different (corecursive) approach to what a “terminating derivation” is.
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- ... arose from considerations valid for coalgebraic semantics of logic programs
- features parallel derivations;
- it is not a standard SLD-resolution any more, e.g. unification is restricted to term matching;

Advantages

- Works uniformly for both inductive and coinductive definitions, without having to classify the two into disjoint sets;
- in spirit of corecursion, derivations may feature an infinite number of finite structures.
- there does not have to be regularity or repeating patterns in derivations.
Questions answered

- What is the difference between “normal” LP and coinductive LP?
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- Is this role of Co-LP specific to FW-JAVA and object-oriented languages, or can be extended to functional languages?
- Can alternative coinductive LP algorithm [CSL’11] be any better for type inference?
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- ... what is the role of \textit{coinductive} LP for type inference?
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Questions answered

- ... what is the role of coinductive LP for type inference?
- Why there is no place for Co-LP in type inference by CLP(X)?
- ... is this role of Co-LP specific to FW-JAVA and object-oriented languages, or can be extended to functional languages?
- ... can alternative coinductive LP algorithm [CSL’11] be any better for type inference?
Why is there no place for Co-LP in type inference by CLP(X)?

The answer is:

CLP(X) uses a restricted form of logic programs - the one that does not allow recursion.

LP, [Sulzmann, Stuckey 2008]

Head $H ::= p(a_1, . . . , a_n)$
Atom $L ::= p(t_1, . . . , t_n)$
Goal $G ::= L \mid C \mid G \land G$
Rule $R ::= H ←$

Type inference by CLP(X) comes with a proof of termination. (Programs are not recursive.)
The trick is due to separating derivations in LP stage and constraint solving stage.
Example of a LP used for type inference:

Example

\[ g \ y = \text{let} \ f \ x = \ x \ \text{in} \ (f \ True, \ f \ y) \]

\[ f(t) \leftarrow t = t_x \rightarrow t \]

\[ g(t) \leftarrow t = t_y \rightarrow (t_1, t_2) \land f(t_{f_1}) \land t_{f_1} = \text{Bool} \rightarrow t_1 \land f(t_{f_2}) \land t_{f_2} = t_y \rightarrow t_2 \]
Example of a LP used for type inference:

Example

g y = let f x = x in (f True, f y)

\[ f(t) \leftarrow t = t_x \rightarrow t \]

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\[ \rightarrow f t = t_y \rightarrow (t_1, t_2) \land t_{f_1} = t_x \rightarrow t_x \land t_{f_1} = \text{Bool} \rightarrow t_1 \land f(t_{f_2}) \land t_{f_2} = t_y \rightarrow t_2 \]
Example of a LP used for type inference:

**Example**

```plaintext
Example

\[ g \ y = \text{let } f \ x = x \ \text{in } (f \ \text{True}, \ f \ y) \]

\[ f(t) \leftarrow t = t_\times \rightarrow t \]

\[ g(t) \leftarrow t = t_y \rightarrow (t_1, t_2) \land f(t_{f_1}) \land t_{f_1} = \text{Bool} \rightarrow t_1 \land f(t_{f_2}) \land t_{f_2} = t_y \rightarrow t_2 \]

\[ \rightarrow f \ t = t_y \rightarrow (t_1, t_2) \land t_{f_1} = t_\times \rightarrow t_\times \land t_{f_1} = \text{Bool} \rightarrow t_1 \land f(t_{f_2}) \land t_{f_2} = t_y \rightarrow t_2 \]

\[ \rightarrow f \ t = t_y \rightarrow (t_1, t_2) \land t_{f_1} = t_\times \rightarrow t_\times \land t_{f_1} = \text{Bool} \rightarrow t_1 \land t_{f_2} = t'_{x} \rightarrow t'_{x} \land \]

\[ t_{f_2} = t_y \rightarrow f_{2} \]
```

**After solving the constraints, g's type is**

\[ \forall t \ y. \ t_\times \rightarrow (\text{Bool}, \ t_y) \]
Example of a LP used for type inference:

Example

\[ g \ y = \text{let } f \ x = x \text{ in } (f \ True, f \ y) \]

\[
f(t) \leftarrow t = t_x \rightarrow t
\]

\[
g(t) \leftarrow t = t_y \rightarrow (t_1, t_2) \land f(t_{f_1}) \land t_{f_1} = Bool \rightarrow t_1 \land f(t_{f_2}) \land t_{f_2} = t_y \rightarrow t_2
\]

\[
\rightarrow_f t = t_y \rightarrow (t_1, t_2) \land t_{f_1} = t_x \rightarrow t_x \land t_{f_1} = Bool \rightarrow t_1 \land f(t_{f_2}) \land t_{f_2} = t_y \rightarrow t_2
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\[
\rightarrow_f t = t_y \rightarrow (t_1, t_2) \land t_{f_1} = t_x \rightarrow t_x \land t_{f_1} = Bool \rightarrow t_1 \land t_{f_2} = t_x' \rightarrow t_x' \land t_{f_2} = t_y \rightarrow f_2
\]

After solving the constraints,

\[ g\text{'s type is } \forall t_y . t_y \rightarrow (Bool, t_y) \]
Features of CLP(X) method:

- Constraints describe types of expressions;
- each rule describes type of a function (hence only 1 rule per function admitted);
- let-bound function names are renamed to guarantee that the rule heads have distinct predicates;
- no explicit type schemes for let-defined functions, only rules;
- polymorphism is achieved by replicating the constraints for let-definitions.
- recursion is handled by equating the type of the recursive call with the type of the function.

Example

\[
f(x) = \text{let } g \text{ y = rec } g \text{ in } \lambda \text{ y. } \ g \text{ x in } g \text{ x}
\]
\[
g(t, l) \leftarrow t = t_y \rightarrow t_1 \land l = [t_x] \land t_g = t_x \rightarrow t_1 \land t_g = t.
\]

- separation of constraint generation and inference;
- flexible and accurate type error diagnosis.
Role of Co-LP in FW-JAVA [Ancona et al. 2008]

[Since TYPES’08, eight (!) more papers by the authors on the subject. Also, incorporating some ideas from Sulzman’s CLP(X).]

A general observation

Object-oriented languages make heavy use of inheritance, interfaces, and method overriding in a word, subtyping. Naively attempting to expand from Damas-Milners unification to solving a set of subtyping inequality constraints results in an instance of the semi-unification problem, which is generally undecidable.
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Problem: a general analysis of the method is lacking, e.g. in statements of adequacy, soundness and completeness.

Method of generating logic programs from typed programs is different from Sulzmann, which makes direct comparison hard. In paricular, I suspect [at least some of] (co)recursive LPs shown in [Ancona et al.] are due to the method difference.
invoke ( obj(C,R),M,A1 ,RT_ET) ← val_types (A1 ,A2),
exc_types (A1 ,ET), has_meth (C,M ,[ obj(C,R) | A2 ],RT ).
invoke ( obj(C,R),M,A,ET) ← no_val_types (A), exc_types
(A,ET ).
invoke (T1_T2 ,M,A,RT1_RT2) ← invoke (T1 ,M,A, RT1), invoke
(T2 ,M,A, RT2 ).
invoke (ex(C),M,A,ex(C )) ←.

Most of such clauses would not be allowed in previous CLP(X)
approach, and would be reformulated:
Example

\[
\text{invoke (obj(C,R),M,A1,RT ET)} \leftarrow \text{val_types (A1,A2),}
\text{exc_types (A1,ET), has_meth (C,M,[obj(C,R) | A2],RT).}
\]
\[
\text{invoke (obj(C,R),M,A,ET)} \leftarrow \text{no_val_types (A), exc_types (A,ET).}
\]
\[
\text{invoke (T1_T2,M,A,RT1_RT2)} \leftarrow \text{invoke (T1,M,A,RT1), invoke (T2,M,A,RT2).}
\]
\[
\text{invoke (ex(C),M,A,ex(C))} \leftarrow .
\]

Most of such clauses would not be allowed in previous CLP(X) approach, and would be reformulated:

E.g. the highlighted clause would be \text{invoke (t,l) \leftarrow t = t_1 \lor t_2, \ldots}.
Doubts summarised

Two major accounts [Ancona & Sulzmann] of LP for type inference present general approaches to formulating a LP + constraints from function definitions. They could be cross applied, subject to careful description of suitable fragments of type systems.

- I am not entirely convinced that type inference in FW Java cannot be done using Sulzmann’s method (terminating LPs); at any rate, this issue is not analysed in the literature;
- If indeed coinductive LPs cannot be avoided for CLP(X) type inference for certain type systems, I am not convinced co-LPs [Simon, Gupta] are expressive enough to handle this – especially, they do not allow to mix inductive and coinductive predicates in one clause and can work only with finite regular patterns (which has to be determined in advance of inference);
- chance for our new coinductive LPs?
Conclusions. Coinductive LP [KP’11] could be useful:

- when delayed/partial type inference may be welcome (on place of infinitary term rewriting? for some mixture of static and dynamic inference?)
- [akin reconciliation of static and dynamic inference mentioned by G.Gonthier yesterday?]
- [Another yesterday’s talk Type Classes: instance resolution cannot handle cyclic instances]
- OR where concurrency and parallelism are important;
- in case combining inductive and coinductive propositions in clauses is important;
- in case a regular pattern in an infinite structure described by a LP either does not exist or is too expensive to observe in advance.
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Research question

Where this could be applied, and how can it be implemented?
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Personal question: Is the RQ worth investigating?
Any Questions?
or, better, Any Answers?